

City University of New York (CUNY)

## CUNY Academic Works

---

Computer Science Technical Reports

CUNY Academic Works

---

2008

### TR-2008014: Why Do We Need Justification Logic?

Sergei Artemov

[How does access to this work benefit you? Let us know!](#)

More information about this work at: [https://academicworks.cuny.edu/gc\\_cs\\_tr/319](https://academicworks.cuny.edu/gc_cs_tr/319)

Discover additional works at: <https://academicworks.cuny.edu>

---

This work is made publicly available by the City University of New York (CUNY).  
Contact: [AcademicWorks@cuny.edu](mailto:AcademicWorks@cuny.edu)

# Why Do We Need Justification Logic?

Sergei Artemov\*

Graduate Center CUNY  
365 Fifth Avenue, New York City, NY 10016  
sartemov@gc.cuny.edu

September 16, 2008

## Abstract

In this paper, we will sketch the basic system of Justification Logic, which is a general logical framework for reasoning about epistemic justification. Justification Logic renders a new, evidence-based foundation for epistemic logic. As a case study, we compare formalizations of the Kripke ‘Red Barn’ scenario in modal epistemic logic and Justification Logic and show here that the latter provides a deeper analysis. In particular, we argue that modal language fails to fully represent the epistemic closure principle whereas Justification Logic provides its adequate formalization.

## 1 Introduction

Since Plato, the notion of justification has been an essential component of epistemic studies (cf. [15; 22; 24; 26; 36; 42; 48], and many others). However, until recently, the notion of justification was conspicuously absent in the mathematical models of knowledge within the epistemic logic framework. Commencing from seminal works [28; 52], the notions of Knowledge and Belief have acquired formalization by means of modal logic with atoms *F is known* and *F is believed*. Within this approach, the following analysis was adopted: For a given agent,

$$F \text{ is known} \quad \sim \quad F \text{ holds in all epistemically possible situations.}$$

The deficiency of this approach is displayed most prominently, in the *Logical Omniscience* feature of the modal logic of knowledge (cf. [17; 18; 29; 41; 44]). This lack of a justification component has, perhaps, contributed to a certain gap between epistemic logic and mainstream epistemology ([26; 27]). We would like to think that Justification Logic is a step towards filling this void.

---

\*This work has been partially supported by NSF grant 0830450, CUNY Collaborative Incentive Research Grant CIRG1424, and PSC CUNY Research Grant PSCREG-39-721

Justification Logic had been anticipated in [23] (as the logic of explicit mathematical proofs) and in [51] (in epistemology), developed in [2; 3; 34; 40] and other papers (as the Logic of Proofs), and then in [4; 5; 6; 8; 12; 20; 21; 25; 31; 33; 43; 45; 47; 53] and other papers in a broader epistemic context. It introduces a long-anticipated mathematical notion of justification, making epistemic logic more expressive. We now have the capacity to reason about justifications, simple and compound. We can compare different pieces of evidence pertaining to the same fact. We can measure the complexity of justifications, which leads to a coherent theory of logical omniscience [7]. Justification Logic provides a novel, evidence-based mechanism of evidence-tracking which seems to be a key ingredient of the analysis of knowledge. Finally, Justification Logic furnishes a new, evidence-based foundation for the logic of knowledge, according to which

$$F \text{ is known} \quad \sim \quad F \text{ has an adequate justification.}$$

Justification assertions have the format  $t:F$ , which is read generically as

$$t \text{ is a justification of } F.$$

There is also a more strict ‘justificationist’ reading in which  $t:F$  is understood as

$$t \text{ is accepted by agent as a justification of } F.$$

Justification Logic is general enough to incorporate other semantics; e.g., the topological semantics of Justification Logic has been studied in [9].

Justification Logic has been built so far on the simplest base: *classical Boolean logic*, and it is a natural next step to extend these ideas to more elaborate logical models, e.g., intuitionistic and substructural logics, conditionals, relevance logics, and logics of counterfactual reasoning. There are several good reasons for choosing a Boolean logic base for our first meaningful step. At this stage, we are concerned first with *justifications*, which provide a sufficiently serious challenge on even the simplest Boolean base. Once this case is sorted out in a satisfactory way, we can move on to incorporating justifications into other logics. Second, Boolean-based Justification Logic seems to cover known paradigmatic examples, e.g., Russell’s and Gettier’s examples ([5]) and Kripke’s Red Barn Example, which we consider below.

Within the Justification Logic framework, we treat both – **justifications**, which do not necessarily yield the truth of a belief, and **factive justifications**, which yield the truth of the belief. This helps to capture the essence of discussion about these matters in epistemology, where justifications are not generally assumed to be factive.

In this paper, we consider the case of one agent only, although multi-agent Justification Logics have already been studied ([4; 8; 53]).

Formal logical methods do not directly solve philosophical problems but rather provide a tool for analyzing assumptions and ensuring that we draw correct conclusions. Our hope is that Justification Logic does just that.

## 2 Justifications and Operations

In order to build a formal account of justification, we will make some basic structural assumptions: justifications are abstract objects which have structure, agents do not lose or forget justifications,

agents apply the laws of classical logic and accept their conclusions, etc.

We assume two basic operations on justifications, *Application* ‘.’ and *Sum* ‘+,’ both having clear epistemic meaning and exact interpretations in relevant mathematical models.

The *Application* operation ‘.’ performs one epistemic action, a one-step deduction according to the *Modus Ponens* rule. Application takes a justification  $s$  of an implication  $F \rightarrow G$  and a justification  $t$  of its antecedent,  $F$ , and produces a justification  $s \cdot t$  of the succedent,  $G$ . Symbolically,

$$s:(F \rightarrow G) \rightarrow (t:F \rightarrow (s \cdot t):G). \quad (1)$$

This is a basic property of justification-type objects assumed in combinatory logic and  $\lambda$ -calculi (cf. [49]), Brouwer-Heyting-Kolmogorov semantics ([50]), Kleene realizability ([30]), the Logic of Proofs LP ([3]), etc. Application principle (1) is related to the epistemic closure principle (cf., for example, [37])

$$\textit{one knows everything that one knows to be implied by what one knows.} \quad (2)$$

However, (1) does not rely on (2), since (1) deals with a broader spectrum of justifications not necessarily linked to knowledge. If justifications  $s$  and  $t$  are formal Hilbert-style proofs, then  $s \cdot t$  can be understood as a new proof obtained from  $s$  and  $t$  by a single application of the rule *Modus Ponens* to all possible premises  $F \rightarrow G$  from  $s$ , and  $F$  from  $t$ :

$$s \cdot t = s * t * \ulcorner G_1 \urcorner * \dots * \ulcorner G_n \urcorner,$$

where  $*$  is concatenation,  $\ulcorner X \urcorner$  denotes the Gödel number of  $X$ , and  $G_i$ 's are all formulas from  $t$  for which there is a formula  $F \rightarrow G_i$  from  $s$ .

The second basic operation *Sum* ‘+’ expresses the idea of pooling evidence together without performing any epistemic action. Operation ‘+’ takes justifications  $s$  and  $t$  and produces  $s + t$ , which is a justification for everything justified by  $s$  or by  $t$ .

$$s:F \rightarrow (s + t):F \quad \text{and} \quad s:F \rightarrow (t + s):F.$$

In the context of formal proofs, the sum ‘ $s + t$ ’ can be interpreted as a concatenation of proofs  $s$  and  $t$

$$s + t = s * t.$$

Such an operation is needed to connect Justification Logic with epistemic modal logic. Justification Logic systems without ‘+’ have been studied in [10; 32; 33].

Justification terms (polynomials) are built from justification variables  $x, y, z, \dots$  and justification constants  $a, b, c, \dots$  by means of the operations ‘.’ and ‘+.’ Constants denote atomic justifications which the system no longer analyzes; variables denote unspecified justifications. For the sake of technical convenience, we assume that each constant comes with indices  $i = 1, 2, 3 \dots$  which we will omit whenever it is safe.

More elaborate Justification Logic systems use additional operations on justifications, e.g., verifier ‘!’ and negative verifier ‘?’ ([3; 5; 43; 46; 47]), but we will not need them in this paper.

### 3 Basic Logic of Justifications

Formulas are built from propositional atoms as the usual formulas of Boolean logic, e.g., by means of logical connectives  $\wedge, \vee, \rightarrow, \neg$  with the additional formation rule:

*Whenever  $t$  is a justification term and  $F$  is a formula,  $t:F$  is again a formula.*

The basic Logic of Justifications  $J_0$  contain the following postulates:

- A1. *Classical propositional axioms and rule Modus Ponens,*
- A2. *Application Axiom  $s:(F \rightarrow G) \rightarrow (t:F \rightarrow (s \cdot t):G)$ ,*
- A3. *Sum Axiom  $s:F \rightarrow (s+t):F$ ,  $s:F \rightarrow (t+s):F$ .*

$J_0$  is the logic of general (not necessarily factive) justifications for an absolutely skeptical agent for whom no formula is provably justified, i.e.,  $J_0$  does not derive  $t:F$  for any  $t$  and  $F$ . Such an agent is, however, capable of making *relative justification conclusions* of the form

*if  $x:A, y:B, \dots, z:C$  hold, then  $t:F$ .*

$J_0$  is able, with this capacity, to adequately emulate other Justification Logic systems within its language.

Well-known examples of epistemic reasoning reveal that logical axioms are often assumed justified. Justification Logic offers a flexible mechanism of *Constant Specifications* that represents different shades of this kind of logical awareness.

Justification Logic distinguishes between assumptions and justified assumptions. Constants are used to denote justifications of assumptions in situations where we don't analyze these justifications further. Suppose we want to postulate that an axiom  $A$  is justified for a given agent. The way to state it in Justification Logic is to postulate

$$e_1:A$$

for some justification constant  $e_1$  with index 1. Furthermore, if we want to postulate that this new principle  $e_1:A$  is also justified, we can postulate

$$e_2:(e_1:A)$$

for the similar constant  $e_2$  with index 2, then

$$e_3:(e_2:(e_1:A)),$$

etc. Using similar constants for 'in-depth justifications' and keeping track of indices is not really necessary, but it is easy and helps in decision procedures (cf. [35]). By  $e_n:e_{n-1}:\dots:e_1:A$ , we mean  $e_n:(e_{n-1}:\dots:(e_1:A)\dots)$ . A set of assumptions of this kind for a given logic is called a *Constant Specification*. Here is a formal definition.

A **Constant Specification**  $CS$  for a given logic  $\mathcal{L}$  is a set of formulas

$$e_n:e_{n-1}:\dots:e_1:A \quad (n \geq 1),$$

in which  $A$  is an axiom of  $\mathcal{L}$ , and  $e_1, e_2, \dots, e_n$  are similar constants with indices  $1, 2, \dots, n$ . We also assume that  $CS$  contains all intermediate specifications, i.e., whenever  $e_n:e_{n-1}:\dots:e_1:A$  is in  $CS$ , then  $e_{n-1}:\dots:e_1:A$  is in  $CS$ , too. Here are typical examples of constant specifications:

- *empty*:  $CS = \emptyset$ . This corresponds to an absolutely skeptical agent (cf. a comment after axioms of  $J_0$ ).
- *finite*:  $CS$  is a finite set of formulas. This is a representative case, since any specific derivation in Justification Logic concerns only finite sets of constants and constant specifications.
- *axiomatically appropriate*: For each axiom  $A$ , there is a constant  $e_1$  such that  $e_1:A$  is in  $CS$ , and if  $e_n:\dots:e_1:A \in CS$ , then  $e_{n+1}:e_n:\dots:e_1:A \in CS$ .
- *total*: For each axiom  $A$  and **any** constants  $e_1, e_2, \dots, e_n$ ,

$$e_n:e_{n-1}:\dots:e_1:A \in CS.$$

Naturally, the total constant specification is axiomatically appropriate.

### Logic of Justifications with given Constant Specification

$$J_{CS} = J_0 + CS.$$

### Logic of Justifications

$$J = J_0 + R4,$$

where R4 is the **Axiom Internalization Rule**:

*For each axiom  $A$  and any constants  $e_1, e_2, \dots, e_n$ , infer  $e_n:e_{n-1}:\dots:e_1:A$ .*

Note that  $J_0$  is  $J_\emptyset$ , and  $J$  is  $J_{CS}$  with the total Constant Specification  $CS$ . The latter reflects the idea of the unrestricted logical awareness for  $J$ . A similar principle appeared in the Logic of Proofs LP.

For each constant specification  $CS$ ,  $J_{CS}$  enjoys the Deduction Theorem because  $J_0$  contains propositional axioms and *Modus Ponens* as the only rule of inference.

Logical awareness expressed by axiomatically appropriate constant specifications ensures an important *Internalization Property* of the system. This property was anticipated by Gödel in [23] for the logic of explicit mathematical proofs, and was first established for the Logic of Proofs LP in [2; 3].

**Theorem 1** For each axiomatically appropriate constant specification  $CS$ ,  $J_{CS}$  enjoys the Internalization Property:

If  $\vdash F$ , then  $\vdash p.F$  for some justification term  $p$ .

**Proof.** Induction on derivation length. If  $F$  is an axiom  $A$ , then, since  $CS$  is axiomatically appropriate, there is a constant  $e_1$  such that  $e_1:A$  is in  $CS$ , hence an axiom of  $J_{CS}$ . If  $F$  is in  $CS$ , then, since  $CS$  is axiomatically appropriate,  $e_n:F$  is in  $CS$  for some constant  $e_n$ . If  $F$  is obtained by *Modus Ponens* from  $X \rightarrow F$  and  $X$ , then, by the Induction Hypothesis,  $\vdash s:(X \rightarrow F)$  and  $\vdash t:X$  for some  $s, t$ . By the Application Axiom,  $\vdash (s \cdot t):F$ .  $\square$

Internalization in  $J$  is an explicit incarnation of the Necessitation Rule in modal logic  $K$ :

$$\vdash F \quad \Rightarrow \quad \vdash \Box F.$$

Let us consider some basic examples of derivations in  $J$ . In Examples 1 and 2, only constants of level 1 have been used; in such situations we skip indices completely.

**Example 1** This example shows how to build a justification of a conjunction from justifications of the conjuncts. In the traditional modal language, this principle is formalized as

$$\Box A \wedge \Box B \rightarrow \Box(A \wedge B).$$

In  $J$  we express this idea in a more precise justification language.

1.  $A \rightarrow (B \rightarrow A \wedge B)$ , a propositional axiom;
2.  $c:[A \rightarrow (B \rightarrow A \wedge B)]$ , from 1, by R4;
3.  $x:A \rightarrow (c \cdot x):(B \rightarrow A \wedge B)$ , from 2, by A2 and *Modus Ponens*;
4.  $x:A \rightarrow (y:B \rightarrow ((c \cdot x) \cdot y):(A \wedge B))$ , from 3, by A2 and some propositional reasoning;
5.  $x:A \wedge y:B \rightarrow ((c \cdot x) \cdot y):(A \wedge B)$ , from 5, by propositional reasoning.

Derived formula 5 contains constant  $c$ , which was introduced in line 2, and the complete reading of the result of this derivation is

$$x:A \wedge y:B \rightarrow ((c \cdot x) \cdot y):(A \wedge B), \text{ given } c:[A \rightarrow (B \rightarrow A \wedge B)].$$

**Example 2** This example shows how to build a justification of a disjunction from justifications of either disjuncts. In the usual modal language, this is represented by

$$\Box A \vee \Box B \rightarrow \Box(A \vee B).$$

Let us see how this would look in  $J$ .

1.  $A \rightarrow A \vee B$ , by A1;
2.  $a:[A \rightarrow A \vee B]$ , from 1, by R4;
3.  $x:A \rightarrow (a \cdot x):(A \vee B)$ , from 2, by A2 and *Modus Ponens*;
4.  $B \rightarrow A \vee B$ , by A1;
5.  $b:[B \rightarrow A \vee B]$ , from 4, by R4;

6.  $y:B \rightarrow (b \cdot y):(A \vee B)$  from 5, by A2 and *Modus Ponens*;
7.  $(a \cdot x):(A \vee B) \rightarrow (a \cdot x + b \cdot y):(A \vee B)$ , by A3;
8.  $(b \cdot y):(A \vee B) \rightarrow (a \cdot x + b \cdot y):(A \vee B)$ , by A3;
9.  $(x:A \vee y:B) \rightarrow (a \cdot x + b \cdot y):(A \vee B)$  from 3, 6, 7, 8, by propositional reasoning.

The complete reading of the result of this derivation is

$$(x:A \vee y:B) \rightarrow (a \cdot x + b \cdot y):(A \vee B), \text{ given } a:[A \rightarrow A \vee B] \text{ and } b:[B \rightarrow A \vee B].$$

These examples, perhaps, leave the (correct) impression that J can emulate derivations in the corresponding modal logic; here it is K, but at the expense of keeping track of specific justifications. A need for such additional bureaucracy requires explanation and illustration, which is the main goal of this paper. Before we proceed to Section 4, in which such an example is provided, we briefly list applications of Justification Logic so far:

- intended provability semantics for Gödel’s provability logic S4 with the Completeness Theorem ([2; 3]);
- formalization of Brouwer-Heyting-Kolmogorov semantics for intuitionistic propositional logic with the Completeness Theorem ([2; 3]);
- a general definition of the Logical Omniscience property and theorems that evidence assertions in Justification Logic are not logically omniscient ([7]);
- an evidence-based approach to Common Knowledge (so-called Justified Common Knowledge) which provides a rigorous epistemic semantics to McCarthy’s ‘any fool knows’ systems ([1; 4; 38]). Justified Common Knowledge offers formal systems which are less restrictive than the usual epistemic logics with Common Knowledge [4];
- formalization of Gettier examples in Justification Logic with missing assumptions and redundancy analysis [5], which demonstrates that Justification Logic methods can be applied in formal epistemology;
- analysis of Knower and Knowability paradoxes ([13; 14]).

The **Correspondence Theorem** ([2; 3; 5; 11; 47]) is a cumulative result stating that for each of major epistemic modal logics K, T, K4, S4, K45, KD45, S5, there is a system of justification terms and a corresponding Justification Logic system (called J, JT, J4, LP, J45, JD45, and JT45) capable of recovering explicit justifications for modalities in any theorem of the original modal logic. This theorem is proven by a variety of methods ranging from cut-elimination in modal logics to semantical proof using Kripke-Fitting models (cf. Section 5).

Complexity issues in Justification Logic have been addressed in [12; 31; 33; 34; 35; 39].

## 4 Red Barn Example and Tracking Justifications

We illustrate new capabilities of Justification Logic on a paradigmatic Red Barn Example which Kripke developed in 1980 (cf. [37], from which we borrow the formulation, with some editing for brevity).

Suppose I am driving through a neighborhood in which, unbeknownst to me, papier-mâché barns are scattered, and I see that the object in front of me is a barn. Because I have barn-before-me percepts, I believe that the object in front of me is a barn. Our intuitions suggest that I fail to know barn. But now suppose that the neighborhood has no fake red barns, and I also notice that the object in front of me is red, so I know a red barn is there. This juxtaposition, being a red barn, which I know, entails there being a barn, which I do not, “is an embarrassment”<sup>1</sup>.

We consider the Red Barn Example a test for theories that explain knowledge. From such a theory, we expect a way to represent what is happening here which maintains epistemic closure principle (2), but also preserves the epistemic structure of the example.

We present formal analysis of the Red Barn Example in epistemic modal logic (subsections 4.1 and 4.2) and in Justification Logic (subsections 4.3 and 4.4). We will show that epistemic modal logic only indicates that there is a problem, whereas Justification Logic provides resolution.

To make our point, we don’t need to formally capture every single detail of the Red Barn story; it suffices to formalize and verify its “entailment” portion. Let

- $B$  be the sentence ‘the object in front of me is a barn,’
- $R$  be the sentence ‘the object in front of me is red.’

### 4.1 Red Barn in Modal Logic of Belief

In our first formalization, logical derivation will be performed in epistemic modal logic with ‘my belief’ modality  $\Box$ . We then externally interpret some of the occurrences of  $\Box$  as ‘knowledge’ according to the problem’s description. In the setting with belief modality  $\Box$ , epistemic closure principle (2) seems to yield

$$\text{if } \Box F \text{ and } \Box(F \rightarrow G) \text{ are both cases of knowledge, then } \Box G \text{ is also knowledge.} \quad (3)$$

The following is a set of natural formal assumptions of the Red Barn Example in the language of epistemic modal logic of belief:

1.  $\Box B$ , ‘I believe that the object in front of me is a barn’;
2.  $\Box(B \wedge R)$ , ‘I believe that the object in front of me is a red barn.’ At the metalevel, we assume that 2 is knowledge, whereas 1 is not knowledge by the problem’s description.

In the basic modal logic of belief  $K$  (hence in other modal logics of belief), the following hold:

---

<sup>1</sup>Dretske [16].

3.  $B \wedge R \rightarrow B$ , as a logical axiom;
4.  $\Box(B \wedge R \rightarrow B)$ , obtained from 3 by Necessitation. As a logical truth, this also qualifies as knowledge.

Within this formalization, it appears that (3) is violated: line 2,  $\Box(B \wedge R)$ , and line 4,  $\Box(B \wedge R \rightarrow B)$  are cases of knowledge whereas  $\Box B$  (line 1) is not knowledge. As we see, the modal language here does not help to resolve this issue, but rather obscures its resolution.

## 4.2 Red Barn in Modal Logic of Knowledge

We will now use epistemic modal logic with ‘my knowledge’ modality  $\mathbf{K}$ . Here is a straightforward formalization of Red Barn Example assumptions:

1.  $\neg \mathbf{K}B$ , ‘I do not know that the object in front of me is a barn’;
2.  $\mathbf{K}(B \wedge R)$ , ‘I know that the object in front of me is a red barn.’

It is easy to see that these assumptions are inconsistent in the modal logic of knowledge. Indeed,

3.  $\mathbf{K}(B \wedge R \rightarrow B)$ , by Necessitation of a propositional axiom;
4.  $\mathbf{K}(B \wedge R) \rightarrow \mathbf{K}B$ , from 3, by modal logic reasoning;
5.  $\mathbf{K}B$ , from 2 and 4, by *Modus Ponens*.

Lines 1 and 5 formally contradict each other.

Hence, the language of modal logic of knowledge leads to an inconsistent set of formal assumptions and does not reflect the structure of the Red Barn Example properly.

## 4.3 Red Barn in Justification Logic of Belief

Justification Logic seems to provide a more fine-grained analysis of the Red Barn Example. In Justification Logic, the epistemic closure principle (2) can be naturally formulated according to Application principle (1) as

$$\text{if } t:F \text{ and } s:(F \rightarrow G) \text{ are both cases of knowledge, then } (s \cdot t):G \text{ is also knowledge.} \quad (4)$$

Note that (4) is more precise than (3). In (4), we do not claim that  $f(s, t):G$  is knowledge for **any** justification  $f(s, t)$  but only for a specific  $f(s, t)$ , which is  $s \cdot t$ , whereas (3) *de facto* postulates a link between premises  $\Box F$ ,  $\Box(F \rightarrow G)$  and the conclusion  $\Box G$ , regardless of how this conclusion was obtained. This is how the ambiguous modal language fails to represent the epistemic closure principle: one cannot claim (3) when justification behind conclusion  $\Box G$  is not linked to those behind premises  $\Box F$  and  $\Box(F \rightarrow G)$ . This is the essence of the Red Barn example, and a peril which Justification Logic naturally avoids by virtue of its explicit language.

We formalize the Red Barn example in J where  $t:F$  is interpreted as

‘I believe  $F$  for reason  $t$ .’

We naturally introduce individual justifications  $u$  for belief that  $B$ , and  $v$  for belief that  $B \wedge R$ . The list of assumptions is

1.  $u:B$ , ‘ $u$  is the reason to believe that the object in front of me is a barn’;
2.  $v:(B \wedge R)$ , ‘ $v$  is the reason to believe that the object in front of me is a red barn.’ On the metalevel, the description states that 2 is a case of knowledge, and not merely a belief, whereas 1 is belief which is not knowledge.

Let us try to reconstruct the reasoning of the agent in J:

3.  $B \wedge R \rightarrow B$ , logical axiom;
4.  $a:[B \wedge R \rightarrow B]$ , from 3, by Axiom Internalization. This is also a case of knowledge;
5.  $v:(B \wedge R) \rightarrow (a \cdot v):B$ , from 4, by Application and *Modus Ponens*;
6.  $(a \cdot v):B$ , from 2 and 5, by *Modus Ponens*.

Closure holds! By reasoning in J, we have concluded that  $(a \cdot v):B$  is a case of knowledge, i.e., ‘I know  $B$  for reason  $a \cdot v$ .’ The fact that  $u:B$  is not a case of knowledge does not spoil the closure principle, since the latter claims knowledge specifically for  $(a \cdot v):B$ . Hence, after observing a red façade, I indeed know  $B$ , but this knowledge has nothing to do with 1, which remains a case of belief rather than of knowledge, and Justification Logic formalization represents this fairly.

#### 4.4 Red Barn in Justification Logic of Knowledge

Within this formalization,  $t:F$  is interpreted as

‘I know  $F$  for reason  $t$ .’

As in Section 4.2, we assume

1.  $\neg u:B$ , ‘ $u$  is not a sufficient reason to know that the object is a barn’;
2.  $v:(B \wedge R)$ , ‘ $v$  is a sufficient reason to know that the object is a red barn.’

This is a perfectly consistent set of assumptions even in the logic of factive justifications

$J + \textit{Factivity Principle } (t:F \rightarrow F)$ .

As in 4.3, we can derive  $(a \cdot v):B$  where  $a:[B \wedge R \rightarrow B]$ , but this does not lead to a contradiction. Claims  $\neg u:B$  and  $(a \cdot v):B$  naturally co-exist. They refer to different justifications  $u$  and  $a \cdot v$  of the same fact  $B$ ; one of them insufficient and the other quite sufficient for my knowledge that  $B$ .

#### 4.5 Red Barn and Formal Epistemic Models

It appears that in 4.3 and 4.4, Justification Logic represents the structure of the Red Barn Example in a reasonable way which was not directly captured by epistemic modal logic.

In all fairness to modal tools, we could imagine a formalization of the Red Barn Example in a sort of bi-modal language with distinct modalities for knowledge and belief, where both claims hold: ‘ $\Box B$ ,’ by perceptual belief that  $B$ , and ‘ $\mathbf{K}B$ ’ for knowledge that  $B$  which is logically derived from perceptual knowledge  $\mathbf{K}(B \wedge R)$ . However, it seems that such a resolution will, intellectually, involve repeating Justification Logic arguments from 4.3 and 4.4 in a way that obscures, rather than reveals, the truth. Such a bi-modal formalization would distinguish  $u:B$  from  $(a \cdot v):B$  not

because they have different reasons (which reflects the true epistemic structure of the problem), but rather because the former is labelled ‘belief’ and the latter ‘knowledge.’ But what if we need to keep track of different unrelated reasons which are all cases of either knowledge or belief? Following this multi-modal approach, we will likely end up with a collection of distinct modalities, each for different reasons, as well as a mounting pile of additional assumptions concerning these modalities – all just to avoid revealing the justification structure of a problem which can easily fit into a very basic justification logic  $J$  with the bare minimum of epistemological assumptions.

## 5 Basic Epistemic Semantics

This section will provide the basics of epistemic semantics for Justification Logic, the main ideas of which have been suggested by Fitting in [20]. The standard epistemic semantics for  $J$  (cf. [5]) has been provided by the proper adaptation of Kripke-Fitting models [20] and Mkrtychev models [40].

A Kripke-Fitting **J-model**  $\mathcal{M} = (W, R, \mathcal{E}, \Vdash)$  is a Kripke model  $(W, R, \Vdash)$  enriched with an **admissible evidence function**  $\mathcal{E}$  such that  $\mathcal{E}(t, F) \subseteq W$  for any justification  $t$  and formula  $F$ . Informally,  $\mathcal{E}(t, F)$  specifies the set of possible worlds where  $t$  is considered admissible evidence for  $F$ . The intended use of  $\mathcal{E}$  is in the truth definition for justification assertions:

$u \Vdash t:F$  if and only if

1.  $F$  holds for all possible situations, i.e.,  $v \Vdash F$  for all  $v$  such that  $uRv$ ;
2.  $t$  is an admissible evidence for  $F$  at  $u$ , i.e.,  $u \in \mathcal{E}(t, F)$ .

An admissible evidence function  $\mathcal{E}$  must satisfy the closure conditions with respect to operations ‘ $\cdot$ ’ and ‘ $+$ ’:

- *Application:*  $\mathcal{E}(s, F \rightarrow G) \cap \mathcal{E}(t, F) \subseteq \mathcal{E}(s \cdot t, G)$ . This condition states that whenever  $s$  is an admissible evidence for  $F \rightarrow G$  and  $t$  is an admissible evidence for  $F$ , their ‘product,’  $s \cdot t$ , is an admissible evidence for  $G$ .
- *Sum:*  $\mathcal{E}(s, F) \cup \mathcal{E}(t, F) \subseteq \mathcal{E}(s + t, F)$ . This condition guarantees that  $s + t$  is an admissible evidence for  $F$  whenever either  $s$  is an admissible evidence for  $F$  or  $t$  is an admissible evidence for  $F$ .

Given a model  $\mathcal{M} = (W, R, \mathcal{E}, \Vdash)$ , the forcing relation  $\Vdash$  is extended from sentence variables to all formulas as follows: for each  $u \in W$ ,

1.  $\Vdash$  respects Boolean connectives at each world ( $u \Vdash F \wedge G$  iff  $u \Vdash F$  and  $u \Vdash G$ ;  $u \Vdash \neg F$  iff  $u \not\Vdash F$ , etc.);
2.  $u \Vdash t:F$  iff  $u \in \mathcal{E}(t, F)$  and  $v \Vdash F$  for every  $v \in W$  with  $uRv$ .

Note that an admissible evidence function  $\mathcal{E}$  may be regarded as a Fagin-Halpern awareness function [19] equipped with the structure of justifications.

A model  $\mathcal{M} = (W, R, \mathcal{E}, \Vdash)$  *respects a Constant Specification CS* at  $u \in W$  if  $u \in \mathcal{E}(c, A)$  for all formulas  $c:A$  from  $CS$ . Furthermore,  $\mathcal{M} = (W, R, \mathcal{E}, \Vdash)$  *respects a Constant Specification CS* if  $\mathcal{M}$  respects  $CS$  at each  $u \in W$ .

**Theorem 2** *For any Constant Specification  $CS$ ,  $J_{CS}$  is sound and complete for the class of all Kripke-Fitting models respecting  $CS$ .*

Mkrtychev semantics is a predecessor of Kripke-Fitting semantics ([40]). *Mkrtychev models* are Kripke-Fitting models with a single world, and the proof of Theorem 2 can be easily modified to establish completeness of  $J_{CS}$  with respect to Mkrtychev models.

**Theorem 3** *For any Constant Specification  $CS$ ,  $J_{CS}$  is sound and complete for the class of Mkrtychev models respecting  $CS$ .*

Theorem 3 shows that the information about Kripke structure in Kripke-Fitting models can be completely encoded by the admissible evidence function. Mkrtychev models play an important theoretical role in Justification Logic [12; 31; 34; 39]. On the other hand, Kripke-Fitting models can be useful as counter-models with desirable properties since they take into account both epistemic Kripke structure and evidence structure. Speaking metaphorically, Kripke-Fitting models naturally reflect two reasons why a certain fact  $F$  can be unknown to an agent:  $F$  fails at some possible world or an agent does not have a sufficient evidence of  $F$ .

Another application area of Kripke-Fitting style models is Justification Logic with both epistemic modalities and justification assertions (cf. [4; 8]).

## 6 Adding Factivity

Factivity states that a given justification of  $F$  is factive, i.e., sufficient for an agent to conclude that  $F$  is true. The corresponding *Factivity Axiom* claims that justifications are factive:

$$t:F \rightarrow F,$$

which has a similar motivation to the Truth Axiom in epistemic modal logic

$$\mathbf{K}F \rightarrow F,$$

widely accepted as a basic property of knowledge.

The Factivity Axiom first appeared in the Logic of Proofs LP as a principal feature of mathematical proofs. Indeed, in this setting Factivity is valid: if there is a mathematical proof  $t$  of  $F$ , then  $F$  must be true.

We adopt the Factivity Axiom for justifications that lead to knowledge. However, factivity alone does not warrant knowledge, which has been demonstrated by Gettier examples ([22]).

### Logic of Factive Justifications:

$$JT_0 = J_0 + \textit{Factivity Axiom},$$

$$JT = J + \textit{Factivity Axiom}.$$

Systems  $JT_{CS}$  corresponding to Constant Specifications  $CS$  are defined similarly to  $J_{CS}$ .

**JT-models** are J-models with reflexive accessibility relations  $R$ . The reflexivity condition makes each possible world accessible from itself, which exactly corresponds to the Factivity Axiom. The direct analogue of Theorem 1 hold for  $JT_{CS}$  as well.

**Theorem 4** For any Constant Specification  $CS$ , each of the logics  $J\mathbb{T}_{CS}$  is sound and complete with respect to the class of JT-models respecting  $CS$ .

**Mkrtychev JT-models** are singleton JT-models, i.e., JT-models with singleton  $W$ 's.

**Theorem 5** For any Constant Specification  $CS$ , each of the logics  $J\mathbb{T}_{CS}$  is sound and complete with respect to the class of Mkrtychev JT-models respecting  $CS$ .

## 7 Conclusions

Modal logic fails to fully represent the epistemic closure principle whereas Justification Logic provides a more adequate formalization.

Justification Logic extends the logic of knowledge by the formal theory of justification. Justification Logic has roots in mainstream epistemology, mathematical logic, computer science, and artificial intelligence. It is capable of formalizing a significant portion of reasoning about justifications.

It remains to be seen to what extent Justification Logic can be useful for analysis of empirical, perceptual, and *a priori* types of knowledge. From the perspective of Justification Logic, such knowledge may be considered as justified by constants (i.e., atomic justifications). Apparently, further discussion is needed here.

## 8 Acknowledgements

The author is very grateful to Walter Dean, Mel Fitting, Vladimir Krupski, Roman Kuznets, Elena Nogina, Tudor Protopopescu, and Ruili Ye, whose advice helped with this paper. Many thanks to Karen Kletter for editing this text.

## References

- [1] E. Antonakos. Justified and Common Knowledge: Limited Conservativity. In S. Artemov and A. Nerode, editors, *Logical Foundations of Computer Science. International Symposium, LFCS 2007, New York, NY, USA, June 2007, Proceedings*, volume 4514 of *Lecture Notes in Computer Science*, pages 1–11. Springer, 2007.
- [2] S. Artemov. Operational modal logic. Technical Report MSI 95-29, Cornell University, 1995.
- [3] S. Artemov. Explicit provability and constructive semantics. *Bulletin of Symbolic Logic*, 7(1):1–36, 2001.
- [4] S. Artemov. Justified common knowledge. *Theoretical Computer Science*, 357(1-3):4–22, 2006.
- [5] S. Artemov. The Logic of Justification. Technical Report TR-2008010, CUNY Ph.D. Program in Computer Science, 2008. To appear in *The Review of Symbolic Logic*.

- [6] S. Artemov, E. Kazakov, and D. Shapiro. Epistemic logic with justifications. Technical Report CFIS 99-12, Cornell University, 1999.
- [7] S. Artemov and R. Kuznets. Logical omniscience via proof complexity. In *Computer Science Logic 2006*, volume 4207, pages 135–149. Springer Lecture Notes in Computer Science, 2006.
- [8] S. Artemov and E. Nogina. Introducing justification into epistemic logic. *Journal of Logic and Computation*, 15(6):1059–1073, 2005.
- [9] S. Artemov and E. Nogina. Topological Semantics of Justification Logic. In E.A. Hirsch, A. Razborov, A. Semenov, and A. Slissenko, editors, *Computer Science Theory and Applications. Third International Computer Science Symposium in Russia, CSR 2008 Moscow, Russia, June 7-12, 2008 Proceedings*, volume 5010 of *Lecture Notes in Computer Science*, pages 30–39. Springer, 2008.
- [10] S. Artemov and T. Strassen. Functionality in the basic logic of proofs. Technical Report IAM 93-004, Department of Computer Science, University of Bern, Switzerland, 1993.
- [11] V. Brezhnev. On the logic of proofs. In *Proceedings of the Sixth ESSLLI Student Session, Helsinki*, pages 35–46, 2001. <http://www.helsinki.fi/esslli/>.
- [12] V. Brezhnev and R. Kuznets. Making knowledge explicit: How hard it is. *Theoretical Computer Science*, 357(1-3):23–34, 2006.
- [13] W. Dean and H. Kurokawa. From the knowability paradox to the existence of proofs. Manuscript (submitted to *Synthese*), 2007.
- [14] W. Dean and H. Kurokawa. The knower paradox and the quantified logic of proofs. In Alexander Hieke, editor, *Austrian Ludwig Wittgenstein Society*, volume 31, August 2008.
- [15] F. Dretske. Conclusive reasons. *Australasian Journal of Philosophy*, 49:1–22, 1971.
- [16] F. Dretske. Is knowledge closed under known entailment? the case against closure. In M. Steup and E. Sosa, editors, *Contemporary Debates in Epistemology*, pages 13–26. Blackwell, 2005.
- [17] R. Fagin and J. Halpern. Belief, awareness, and limited reasoning: Preliminary report. In *Proceedings of the Ninth International Joint Conference on Artificial Intelligence (IJCAI-85)*, pages 491–501, 1985.
- [18] R. Fagin and J. Halpern. Belief, awareness, and limited reasoning. *Artificial Intelligence*, 34(1):39–76, 1988.
- [19] R. Fagin, J. Halpern, Y. Moses, and M. Vardi. *Reasoning About Knowledge*. MIT Press, 1995.
- [20] M. Fitting. The logic of proofs, semantically. *Annals of Pure and Applied Logic*, 132(1):1–25, 2005.

- [21] M. Fitting. A quantified logic of evidence. *Annals of Pure and Applied Logic*, 152(1–3):67–83, March 2008.
- [22] E. Gettier. Is Justified True Belief Knowledge? *Analysis*, 23:121–123, 1963.
- [23] K. Gödel. Vortrag bei Zilsel/Lecture at Zilsel’s (\*1938a). In Solomon Feferman, John W. Dawson, Jr., Warren Goldfarb, Charles Parsons, and Robert M. Solovay, editors, *Unpublished essays and lectures*, volume III of *Kurt Gödel Collected Works*, pages 86–113. Oxford University Press, 1995.
- [24] A. Goldman. A causal theory of knowing. *The Journal of Philosophy*, 64:335–372, 1967.
- [25] E. Goris. Feasible operations on proofs: The Logic of Proofs for bounded arithmetic. *Theory of Computing Systems*, 43(2):185–203, August 2008. Published online in October 2007.
- [26] V.F. Hendricks. Active Agents. *Journal of Logic, Language and Information*, 12(4):469–495, 2003.
- [27] V.F. Hendricks. *Mainstream and Formal Epistemology*. New York: Cambridge University Press, 2005.
- [28] J. Hintikka. *Knowledge and Belief*. Cornell University Press, Ithaca, 1962.
- [29] J. Hintikka. Impossible possible worlds vindicated. *Journal of Philosophical Logic*, 4:475–484, 1975.
- [30] S. Kleene. On the interpretation of intuitionistic number theory. *The Journal of Symbolic Logic*, 10(4):109–124, 1945.
- [31] N.V. Krupski. On the complexity of the reflected logic of proofs. *Theoretical Computer Science*, 357(1):136–142, 2006.
- [32] V.N. Krupski. The single-conclusion proof logic and inference rules specification. *Annals of Pure and Applied Logic*, 113(1-3):181–206, 2001.
- [33] V.N. Krupski. Referential logic of proofs. *Theoretical Computer Science*, 357(1):143–166, 2006.
- [34] R. Kuznets. On the complexity of explicit modal logics. In *Computer Science Logic 2000*, volume 1862 of *Lecture Notes in Computer Science*, pages 371–383. Springer-Verlag, 2000.
- [35] R. Kuznets. *Complexity Issues in Justification Logic*. PhD thesis, CUNY Graduate Center, 2008. <http://kuznets.googlepages.com/PhD.pdf>.
- [36] K. Lehrer and T. Paxson. Knowledge: undefeated justified true belief. *The Journal of Philosophy*, 66:1–22, 1969.
- [37] S. Luper. The epistemic closure principle. *Stanford Encyclopedia of Philosophy*, 2005.

- [38] J. McCarthy, M. Sato, T. Hayashi, and S. Igarishi. On the model theory of knowledge. Technical Report STAN-CS-78-667, Stanford University, 1978.
- [39] R. Milnikel. Derivability in certain subsystems of the Logic of Proofs is  $\Pi_2^P$ -complete. *Annals of Pure and Applied Logic*, 145(3):223–239, 2007.
- [40] A. Mkrtychev. Models for the logic of proofs. In S. Adian and A. Nerode, editors, *Logical Foundations of Computer Science '97, Yaroslavl'*, volume 1234 of *Lecture Notes in Computer Science*, pages 266–275. Springer, 1997.
- [41] Y. Moses. Resource-bounded knowledge. In M. Vardi, editor, *Proceedings of the Second Conference on Theoretical Aspects of Reasoning about Knowledge, March 7–9, 1988, Pacific Grove, California*, pages 261–276. Morgan Kaufmann Pbl., 1988.
- [42] R. Nozick. *Philosophical Explanations*. Harvard University Press, 1981.
- [43] E. Pacuit. A note on some explicit modal logics. Technical Report PP-2006-29, University of Amsterdam. ILLC Publications, 2006.
- [44] R. Parikh. Knowledge and the problem of logical omniscience. In Z. Ras and M. Zemankova, editors, *ISMIS-87 (International Symposium on Methodology for Intellectual Systems)*, pages 432–439. North-Holland, 1987.
- [45] B. Renne. *Dynamic Epistemic Logic with Justification*. PhD thesis, CUNY Graduate Center, May 2008.
- [46] N. Rubtsova. Evidence Reconstruction of Epistemic Modal Logic S5. In *Computer Science - Theory and Applications. CSR 2006*, volume 3967 of *Lecture Notes in Computer Science*, pages 313–321. Springer, 2006.
- [47] N. Rubtsova. On Realization of S5-modality by Evidence Terms. *Journal of Logic and Computation*, 16:671–684, 2006.
- [48] R.C. Stalnaker. Knowledge, Belief and Counterfactual Reasoning in Games. *Economics and Philosophy*, 12:133–163, 1996.
- [49] A.S. Troelstra and H. Schwichtenberg. *Basic Proof Theory*. Cambridge University Press, Amsterdam, 1996.
- [50] A.S. Troelstra and D. van Dalen. *Constructivism in Mathematics, Vols 1, 2*. North-Holland, Amsterdam, 1988.
- [51] J. van Benthem. Reflections on epistemic logic. *Logique & Analyse*, 133-134:5–14, 1993.
- [52] G.H. von Wright. *An essay in modal logic*. North-Holland, Amsterdam, 1951.
- [53] T. Yavorskaya (Sidon). Multi-agent Explicit Knowledge. In D. Grigoriev, J. Harrison, and E.A. Hirsch, editors, *Computer Science - Theory and Applications. CSR 2006*, volume 3967 of *Lecture Notes in Computer Science*, pages 369–380. Springer, 2006.